

FLUX ON COMPACT SYMPLECTIC-CONTACT MANIFOLDS

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ABSTRACT. We introduce flux homomorphism and flux group on a closed symplectic manifold. And on a compact symplectic-contact manifold $(M, \omega, \partial M, \alpha)$ we construct a flux homomorphism and investigate the flux group.

1. INTRODUCTION

In this section, we introduce basic definitions and the flux conjecture. We begin with a closed manifold (M, ω) . Let $\text{Symp}_0(M, \omega)$ be the identity component of the group of the symplectic diffeomorphisms of M , and $\widetilde{\text{Symp}}_0(M, \omega)$ the universal cover of $\text{Symp}_0(M)$. A point in $\widetilde{\text{Symp}}_0(M)$ is a homotopy class of smooth paths $\phi_t \in \text{Symp}_0(M)$ with fixed endpoints $\phi_0 = id$ and $\phi_1 = \phi$. Denote by $\{\phi_t\}$ such a homotopy class. Then the flux homomorphism $F : \widetilde{\text{Symp}}_0(M) \rightarrow H^1(M; \mathbb{R})$ is defined by

$$F(\{\phi_t\}) = \int_0^1 [\iota(X_t)\omega]dt,$$

where the symplectic vector field X_t satisfies $X_t \circ \phi_t = \frac{d}{dt}\phi_t$ and $\iota(X_t)\omega$ is the contraction of ω by the X_t . This homomorphism depends only on the homotopy class of the path ϕ_t . Recall that a path is Hamiltonian if its generating family $\iota(X_t)\omega$ is exact at each time t . Let us denote by $\text{Ham}(M)$ the group of Hamiltonian diffeomorphisms, that is the one of elements of $\text{Symp}_0(M)$ which are endpoints of Hamiltonian paths and by $\widetilde{\text{Ham}}(M)$ the universal cover of $\text{Ham}(M)$. We define the flux group Γ of $H^1(M; \mathbb{R})$ to be the image by F of loops in $\widetilde{\text{Symp}}_0(M)$:

$$\Gamma = \text{Image}\{F : \pi_1(\widetilde{\text{Symp}}_0(M)) \rightarrow H^1(M; \mathbb{R})\}.$$

Theorem 1.1 [M.S]. *Let $\{\phi_t\}$ be a path of symplectic diffeomorphisms. Then $\{\phi_t\}$ is isotopic to a Hamiltonian isotopy with fixed endpoints if and only if $F(\{\phi_t\}) = 0$.*

Theorem 1.2. *Let $\{\phi_t\}$ be a path of symplectic diffeomorphisms. Then the endpoint $\phi_1 = \phi$ is a Hamiltonian diffeomorphism if and only if $F(\{\phi_t\}) \in \Gamma$.*

Proof. First we suppose that the end point $\phi_1 = \phi$ is an element in $\text{Ham}(M)$ for given path $\{\phi_t\}$ of symplectic diffeomorphisms. Thus there exists a path $\{\psi_t\}$ of

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Hamiltonian diffeomorphisms from $\psi_0 = \text{id.}$ to $\psi_1 = \phi = \phi_1$. From Theorem 1.1 we can obtain a loop $\{\psi_t^{-1} \circ \phi_t\} \in \pi_1(\text{Symp}(M))$ satisfying

$$\begin{aligned} F(\{\psi_t^{-1} \circ \phi_t\}) &= F(\{\psi_t^{-1}\}) + F(\{\phi_t\}) \\ &= F(\{\phi_t\}). \end{aligned}$$

The second equality induced from the fact that $\{\psi_t^{-1}\}$ is a path of Hamiltonian diffeomorphisms. This proves that $F(\{\phi_t\}) \in \Gamma$. Inversely, we assume $F(\{\phi_t\}) \in \Gamma$. Then there exists a loop $\{\psi_t\}$ satisfying $F(\{\phi_t\}) = F(\{\psi_t\})$. Thus we can find a loop $\{\phi_t'^{-1} \circ \phi_t\}$ is homotopic to $\{\psi_t\}$, where $\{\phi_t'\}$ is a path from $\phi'_0 = \text{id.}$ to $\phi'_1 = \phi = \phi_1$. From this

$$\begin{aligned} F(\{\phi_t\}) &= F\{\psi_t\} \\ &= F(\{\phi_t'^{-1} \circ \phi_t\}) \\ &= F(\{\phi_t'^{-1}\}) + F(\{\phi_t\}) \end{aligned}$$

and hence $F(\{\phi_t'^{-1}\}) = 0$. By Theorem 1.1 $\{\phi_t'\}$ is a path of Hamiltonian diffeomorphisms and the end point $\phi'_1 = \phi = \phi_1$ is a Hamiltonian diffeomorphism. \square

From Theorems 1.1 and 1.2 there are exact sequences:

1. $0 \rightarrow \widetilde{\text{Ham}}(M) \rightarrow \widetilde{\text{Symp}}_0(M) \rightarrow H^1(M; \mathbb{R}) \rightarrow 0$,
2. $0 \rightarrow \text{Ham}(M) \rightarrow \text{Symp}_0(M) \rightarrow H^1(M; \mathbb{R})/\Gamma \rightarrow 0$.

Remark 1.3 [M.S]. The above concepts make sense for noncompact manifolds without boundary. So there exists an exact sequence under compact-open topology:

$$0 \rightarrow \text{Ham}(M) \rightarrow \text{Symp}_0(M) \rightarrow H^1(M; \mathbb{R})/\Gamma \rightarrow 0$$

Theorem 1.4 [L.M.P1]. *For any closed symplectic manifold, Γ is discrete if and only if the subgroup of Hamiltonian diffeomorphisms is C^1 -closed in the full group of (symplectic) diffeomorphisms of the manifold.*

We can now state the main conjecture as following two equivalent statements.

Flux Conjecture.

1. *For any symplectic manifold, $\text{Ham}(M)$ is C^1 -closed in $\text{Symp}_0(M)$.*
2. *For any closed symplectic manifold, the flux group Γ is discrete.*

2. FLUX HOMOMORPHISM ON COMPACT SYMPLECTIC-CONTACT MANIFOLDS

In this section we would like to introduce compact symplectic-contact manifolds and construct the flux homomorphism on compact symplectic-contact manifolds using the flux homomorphism on the noncompact manifolds which is well defined. Let (M, ω, C, α) be a symplectic-contact manifold such that (M, ω) is an open symplectic manifold with compactification $\bar{M} = M \cup C$ and (C, α) is a contact manifold with a contact 1-form α satisfying $d\alpha = \omega|_C$. A symplectic-contact manifold (M, ω, C, α) is compact if $C = \partial M$. This means that (M, ω) is a symplectic manifold with contact type boundary $(\partial M, \alpha)$. We denote by $(M, \omega, \partial M, \alpha)$ a compact symplectic-contact manifold. From now on we consider a symplectic-contact manifold as a compact one when no specific mention is made.

Lemma 2.1[D.S]. *Let (C, α) be a contact manifold. Then $\psi : C \rightarrow C$ is a contactomorphism with $\psi^*\alpha = \alpha$ if and only if $\phi : C \times \mathbb{R} \rightarrow C \times \mathbb{R}$ is a symplectomorphism on $(C \times \mathbb{R}, d(e^s\alpha))$ where ϕ is defined as $\phi(m, s) = (\psi(m), s)$ for $q = (m, s) \in C \times \mathbb{R}$.*

Theorem 2.2. *For any compact symplectic-contact manifold $(M, \omega, \partial M, \alpha)$, there exists a symplectic form $\tilde{\omega}$ on the noncompact manifold $(\tilde{M}, \tilde{\omega}) = (M \cup \partial M \times (-\varepsilon, \infty), \tilde{\omega})$, which is defined by*

$$\tilde{\omega}_q = \begin{cases} \omega_q & \text{if } q \in M, \\ d(e^s\alpha) = e^s(d\alpha - \alpha \wedge ds) & \text{if } q = (m, s) \in \partial M \times [0, \infty). \end{cases}$$

Proof. Consider an embedding $\Phi : \partial M \times (-\varepsilon, 0] \rightarrow M$ of codimension 0 such that

$$\begin{aligned} \Phi(m, 0) &= m \in \partial M \quad \text{on } (m, 0) \in \partial M \times \{0\} \quad \text{and} \\ \Phi^*\omega(m, s) &= d(e^s\alpha)(m, s) \quad \text{on } (m, s) \in \partial M \times (-\varepsilon, 0]. \end{aligned}$$

If $q = (m, s) \in \partial M \times \{0\} = \partial M$, since $\frac{\partial}{\partial s}$ is transverse to $\partial M = \partial M \times \{0\}$,

$$\begin{aligned} \Phi^*\omega(m, s)|_{\partial M \times \{0\}} &= d(e^s\alpha)|_{\partial M \times \{0\}} \\ &= e^s(d\alpha - \alpha \wedge ds)|_{\partial M \times \{0\}} \\ &= d\alpha. \end{aligned}$$

Gluing (M, ω) and $(\partial M \times (-\varepsilon, \infty), d(e^s\alpha))$ by the map Φ , we can obtain a symplectic manifold $(\tilde{M}, \tilde{\omega}) = (M \cup \partial M \times (-\varepsilon, \infty), \tilde{\omega})$ as follows.

We identify a neighborhood of ∂M in M with $\partial M \times (-\varepsilon, 0]$ in $\partial M \times (-\varepsilon, \infty)$ using Φ . Choosing ε' small enough, we can make $\phi_t[\Phi(\partial M \times (-\varepsilon', 0])] \subset \text{Image}(\Phi)$ for all $t \in [0, 1]$. Then $\Phi^{-1} \circ \phi_t \circ \Phi : \partial M \times (-\varepsilon', 0] \rightarrow \partial M \times (-\varepsilon, 0] \subset \partial M \times (-\varepsilon, \infty)$ is an embedding of codimension 0. On $\partial M = \partial M \times \{0\}$

$$\Phi^{-1} \circ \phi_t \circ \Phi(m, 0) = \Phi^{-1} \circ \phi_t|_{\partial M}(m) = \Phi_0^{-1}(\psi_t(m)) = (\psi_t(m), 0),$$

where $\psi_t = \phi_t|_{\partial M} : \partial M \rightarrow \partial M$ is a contactomorphism and $\Phi_s(m) := \Phi|_{\partial M \times \{s\}}(m)$. Then \tilde{M} is the manifold that we desired. \square

Theorem 2.3. *Let $\{\phi_t\}$ be a path in $\text{Symp}_0(M)$. Then $\{\phi_t\}$ can be extended to a homotopy equivalent path $\{\tilde{\phi}_t\}$ in $\text{Symp}_0(\tilde{M})$.*

Proof. Define $\tilde{\phi}_t : \tilde{M} \rightarrow \tilde{M}$ by

$$\tilde{\phi}_t(q) = \begin{cases} \phi_t(q) & \text{if } q \in M, \\ (\psi_t(m), s) & \text{if } q = (m, s) \in \partial M \times [0, \infty), \end{cases}$$

where $\psi_t(m) = \phi_t|_{\partial M}(m)$ is a contactomorphism on ∂M . From Lemma 2.1 we find that $\tilde{\phi}_t|_{\partial M \times [1, \infty)} = (\psi_t(m), s)$ is a symplectomorphism and $\tilde{\phi}_t^*\tilde{\omega}|_M = \phi_t^*\omega = \omega$. Then $\tilde{\phi}$ is a well-defined symplectomorphism. \square

We denote $X_t \circ \phi_t = \frac{d}{dt}\phi_t$, $\chi_t \circ \psi_t = \frac{d}{dt}\psi_t$. Then we have

$$\frac{d}{dt}\tilde{\phi}_t(q) = \begin{cases} X_t \circ \phi_t(q) & \text{if } q \in M, \\ (\chi_t \circ \psi_t(m), 0) & \text{if } q = (m, s) \in \partial M \times [0, \infty). \end{cases}$$

Thus we have

$$\iota(\tilde{X}_t)\tilde{\omega}_q = \begin{cases} \iota(X_t)\omega_q & \text{if } q \in M, \\ \iota(\chi_t(m))d(e^s\alpha) & \text{if } q = (m, s) \in \partial M \times [0, \infty). \end{cases} \quad (2.1)$$

Recall that the flux homomorphism on the noncompact manifold $(\tilde{M}, \tilde{\omega})$ is well defined (Remark 1.3) and that the inclusion $i : M \rightarrow \tilde{M}$ induces the isomorphism $i^* : H^1(\tilde{M}, \mathbb{R}) \rightarrow H^1(M, \mathbb{R})$. Using the extension $\{\tilde{\phi}_t\}$ of the path $\{\phi_t\}$, we can define the flux homomorphism on compact symplectic-contact manifolds M , $F : \widetilde{\text{Symp}}_0(M) \rightarrow H^1(M; \mathbb{R})$, as $F(\{\phi_t\}) := i^*(\int_0^1 [\iota(\tilde{X}_t)\tilde{\omega}] dt)$.

3. FLUX CONJECTURE ON COMPACT SYMPLECTIC-CONTACT MANIFOLDS

We would like to investigate flux group Γ on compact symplectic-contact manifolds and prove the flux conjecture with some restricted condition. We can check easily that Theorem 1.1 and Theorem 1.2 hold for compact symplectic-contact manifolds. The Theorems in this section are to be proved in another paper of mine.

Theorem 3.1. *Let M be a compact symplectic-contact manifold and $F : \widetilde{\text{Symp}}_0(M) \rightarrow H^1(M; \mathbb{R})$ is the flux homomorphism. Then there exists a right inverse $s : H^1(M; \mathbb{R}) \rightarrow \widetilde{\text{Symp}}_0(M)$ of F such that $F \circ s = id$.*

From this theorem we get the surjectivity of flux homomorphism on symplectic-contact manifolds. Thus there exist exact sequences for a compact symplectic-contact manifold $(M, \omega, \partial M, \alpha)$:

1. $0 \rightarrow \widetilde{\text{Ham}}(M) \rightarrow \widetilde{\text{Symp}}_0(M) \rightarrow H^1(M; \mathbb{R}) \rightarrow 0$
2. $0 \rightarrow \text{Ham}(M) \rightarrow \text{Symp}_0(M) \rightarrow H^1(M; \mathbb{R})/\Gamma \rightarrow 0$,

and Theorem 1.4 can be extended to a compact case as follow.

Theorem 3.2. *For any compact symplectic manifold which may have a contact boundary, Γ is discrete if and only if the subgroup of Hamiltonian diffeomorphisms is C^1 -closed in the full group of (symplectic) diffeomorphisms of the manifold.*

Thus we can state the flux conjecture for a compact symplectic-contact manifold as following two equivalent statements:

Flux Conjecture.

1. *For a compact symplectic-contact manifold, $\text{Ham}(M)$ is C^1 -closed in $\text{Symp}_0(M)$.*
2. *For a compact symplectic-contact manifold, The flux group Γ is discrete.*

Indeed, it suffices to check the discreteness of the flux group Γ in order to prove the flux conjecture.

Theorem 3.2. *Let M be a compact symplectic-contact manifold. Then the flux conjecture holds for the following cases:*

1. *M is a Lefschetz manifold and $H^{2n-2}(\partial M) = 0$.*
2. *M has a symplectic torus action.*
3. *M is spherically rational.*
4. *The first betti number equals to 1.*

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